

# CLIO SOFTWARE RELEASE 4.0: DATA FILES STRUCTURE

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## Introduction

This articles covers the data files of CLIO software version 4.0.

The variable types, native in Borland Pascal, can be summarized as follows:

Byte	:	unsigned 8-bit
Word	:	unsigned 16-bit
Integer	:	signed 16-bit
Longint	:	signed 32-bit
Single	:	floating point (single precision IEEE 754/854 standard)
Boolean	:	8-bit ordinal 0 or 1
Char	:	8-bit ASCII character
String	:	sequence of 8-bit ASCII characters preceded by its 8-bit size attribute

## FFT files (“.FFT” extension)

WrHead = Record

Nome	: String[11];	{12 bytes — usually “AUDIOMATICA”}
Programma	: String[8];	{9 bytes - usually “CLIO”}
Release	: String[4];	{5 bytes - software release}
Comm1	: String[40];	{41 bytes - comment}
Comm2	: String[40];	{41 bytes - comment}
Comm3	: String[40];	{41 bytes - comment}
Comm4	: String[106];	{107 bytes - comment}

end;

FFTText = Record

Titolo	: String[8];	{9 bytes – file name}
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```

Commento : String[50];           {51 bytes – user input comment (with About)}
end;
FFTLocals = Record
  Fcamp    : Word;               {2 bytes – sampling frequency}
  Mode     : MisUnit;           {1 byte – measuring mode (Volt, Pressure)}
  MicASens : Single;            {4 bytes – A channel sensitivity}
  MicBSens : Single;            {4 bytes – B channel sensitivity}
  SensUnits : UnitsType;        {1 byte – sensitivity units (mV/Pa, dBV/Pa, dBspl/V)}
  MicCal   : Boolean;           {1 byte – microphone calibration switch}
  FullScale : Single;           {4 bytes – top of screen value}
  Channel  : AcquiMode;         {1 byte – input channel (A,B,A-B)}
end;
FFTSet = Record
  NumPoints : integer;          {2 bytes – FFT size}
  Nbit      : integer;          {2 bytes – FFT order}
  NumAcqui  : integer;          {2 bytes – number of input samples}
  Average   : boolean;          {1 byte – average mode switch}
  NuAvgStop : word;             {2 bytes – number of target averages}
  NumAverage: integer;          {2 bytes – number of averages performed}
  Window    : FFTWindowType;    {1 byte - type of window
(Hanning,Hamming,Blackman,Bartlett)}
  WindowState: boolean;         {1 byte – window mode switch}
  IntTrg     : boolean;         {1 byte – internal trigger switch}
  IntTrgDelay : integer;        {2 bytes – internal trigger delay}
  Off1       : boolean;         {1 byte – display 1 off switch}
  Off2       : boolean;         {1 byte - display 2 off switch}
  Graph1     = Record
    What     : ChannelOn;        {1 byte – display 1 channel (A,B,A-B,A/B)}
    Ykind    : FFTYAxisKind;     {1 byte – display 1 function (Mag,Real,Imag)}
    Yaxis    : FFTYAxis;         {1 byte – display 1 y axis mode (linear,dB)}
    Xaxis    : FFTXAxis;         {1 byte – display 1 x axis mode (linear,logarithmic)}
  end;
  Graph2     = Record
    What     : ChannelOn;        {1 byte – display 2 channel (A,B,A-B,A/B)}
    Ykind    : FFTYAxisKind;     {1 byte – display 2 function (Mag,Real,Imag)}
    Yaxis    : FFTYAxis;         {1 byte – display 2 y axis mode (linear,dB)}
    Xaxis    : FFTXAxis;         {1 byte – display 2 x axis mode (linear,logarithmic)}
  end;
  Disp1      = Record
    Fscale   : Single;           {4 bytes – display 1 full scale value}
    FscaleI  : Integer;          {2 bytes – display 1 full scale index}
    IncScale : Single;           {4 bytes – display 1 scale increment value}
    Incl     : Integer;          {2 bytes – display 1 scale increment index}
    Span     : Single;           {4 bytes – display 1 total span value}
  end;
  Disp2      = Record
    Fscale   : Single;           {4 bytes – display 2 full scale value}
    FscaleI  : Integer;          {2 bytes – display 2 full scale index}
    IncScale : Single;           {4 bytes – display 2 scale increment value}
    Incl     : Integer;          {2 bytes – display 2 scale increment index}
    Span     : Single;           {4 bytes – display 2 total span value}
  end;
end;

```

```

MaxIndex : integer;           {2 bytes – last FFT value index}
end;
FFTOut.A = Array [0..FFTSet.MaxIndex] Of  {(4*FFTSet.Maxindex) bytes – FFT channel A
data}
    Complex = Record
        Re : Single;           {4 bytes – real part}
        Im : Single;           {4 bytes – imag part}
    end;
FFTOut.B = Array [0..FFTSet.MaxIndex] Of  {(4*FFTSet.Maxindex) bytes – FFT channel B
data}
    Complex = Record
        Re : Single;           {4 bytes – real part}
        Im : Single;           {4 bytes – imag part}
    end;

```

\*\* The following part is present only in averaged FFTs.

```

NumAverage : integer;           {2 bytes – number of averages performed}
FFTVal.1.Data =Array [0..FFTSet.MaxIndex] Of  {(4*FFTSet.Maxindex) bytes – FFT chan-
nel A average data}
    FFTData = Record
        Inst : single;         {4 bytes – instantaneous value}
        Avg : single;         {4 bytes – averaged value}
    end;
FFTVal.2.Data =Array [0..FFTSet.MaxIndex] Of  {(4*FFTSet.Maxindex) bytes – FFT chan-
nel B average data}
    FFTData = Record
        Inst : single;         {4 bytes – instantaneous value}
        Avg : single;         {4 bytes – averaged value}
    end;

```

Total bytes count = variable.

## MLS files (".MLS" extension)

```

WrHead = Record
    Nome      : String[11];     {12 bytes — usually "AUDIOMATICA"}
    Programma : String[8];     {9 bytes - usually "CLIO"}
    Release   : String[4];     {5 bytes - software release}
    Comm1     : String[40];    {41 bytes - comment}
    Comm2     : String[40];    {41 bytes - comment}
    Comm3     : String[40];    {41 bytes - comment}
    Comm4     : String[106];   {107 bytes - comment}
end;
MLSText = Record
    Titolo    : String[8];     {9 bytes – file name}
    Commento  : String[50];    {51 bytes – user input comment (with About)}
end;
MLSLocals = Record
    Fcamp     : Word;          {2 bytes – sampling frequency}
    Mode      : MisUnit;       {1 byte – measuring mode (Volt, Pressure)}

```

```

MicASens : Single;           {4 bytes – A channel sensitivity}
MicBSens : Single;           {4 bytes – B channel sensitivity}
SensUnits : UnitsType;      {1 byte – sensitivity units (mV/Pa, dBV/Pa, dBspl/V)}
MicCal    : Boolean;         {1 byte – microphone calibration switch}
FullScale : Single;          {4 bytes – top of screen value}
Channel   : AcquiMode;       {1 byte – input channel (A,B,A-B)}
end;
MLSSet = Record
  dBRange : byte             {1 byte – amplitude scale range (20,10,5,2,1 dB/div)}
  FreqStart : byte           {1 byte – x-axis start frequency (20,200,2000 Hz)}
  Smooth    : byte           {1 byte – smoothing factor (no, 1/2, 1/3, 1/6, 1/12 octave)}
  PhKind    : byte           {1 byte – kind of phase data (Normal, Minimum,
DelayFree)}
  NuAvg     : integer         {2 bytes – number of averages}
  AvgMode   : byte           {1 byte – kind of average mode (Continuous, Manual)}
  TimeW     : byte           {1 byte – time window (no, HalfHann, Hann, HalfBH,
BH)}
  BeginPoint : integer;       {2 bytes – first sample of selected impulse}
  EndPoint   : integer;       {2 bytes – last sample of selected impulse}
end;
MLSSinglePulse= array [0..16382] of single; {65532 bytes – impulse data}
***
= array [0..2] of byte; {3 bytes – reserved}
MLSXReal = array [0..4095] of single; {16384 bytes – FFT real part}
MLSXImag = array [0..4095] of single; {16384 bytes – FFT imag part}

```

Total bytes count = 98649 bytes.

## Waterfall files (“.WTF” extension)

```

WrHead = Record
  Nome      : String[11];     {12 bytes — usually “AUDIOMATICA”}
  Programma : String[8];     {9 bytes - usually “CLIO”}
  Release   : String[4];     {5 bytes - software release}
  Comm1     : String[40];    {41 bytes - comment}
  Comm2     : String[40];    {41 bytes - comment}
  Comm3     : String[40];    {41 bytes - comment}
  Comm4     : String[106];   {107 bytes - comment}
end;
WTFText = Record
  Titolo    : String[8];     {9 bytes – file name}
  Commento  : String[50];    {51 bytes – user comment (input with About)}
end;
WTFSet = Record
  Tot_Spec  : integer;       {2 bytes – total number of spectra}
  End_Spec  : integer;       {2 bytes – last transform sample}
  FrStart   : integer;       {2 bytes – start frequency}
  Wtf_d     : integer;       {2 bytes – no care}
  SmoothState: boolean;     {1 byte – smoothing switch}
  Wtf_f     : boolean;       {1 byte – no care}
end;
WTFSave = array [0..399,0..30] of byte; {12400 bytes – waterfall data}

```

Total bytes count = 12726 bytes.

## Sinusoidal Frequency Response files (".FRS" extension)

WrHead = Record

Nome : String[11]; {12 bytes — usually "AUDIOMATICA"}  
Programma : String[8]; {9 bytes - usually "CLIO"}  
Release : String[4]; {5 bytes - software release}  
Comm1 : String[40]; {41 bytes - comment}  
Comm2 : String[40]; {41 bytes - comment}  
Comm3 : String[40]; {41 bytes - comment}  
Comm4 : String[106]; {107 bytes - comment}

end;

FRSText = Record

Titolo : String[8]; {9 bytes – file name}  
Commento : String[50]; {51 bytes – user comment (input with About)}

end;

FRSLocals = Record

Fcamp : Word; {2 bytes – sampling frequency}  
Mode : MisUnit; {1 byte – measuring mode (Volt, Pressure)}  
MicASens : Single; {4 bytes – A channel sensitivity}  
MicBSens : Single; {4 bytes – B channel sensitivity}  
SensUnits : UnitsType; {1 byte – sensitivity units (mV/Pa, dBV/Pa, dBspl/V)}  
MicCal : Boolean; {1 byte – microphone calibration switch}  
FullScale : Single; {4 bytes – top of screen value}  
Channel : AcquiMode; {1 byte – input channel (A,B,A-B)}

end;

FRSSet = Record

dBRange : byte {1 byte – amplitude scale range (20,10,5,2,1 dB/div)}  
FrsFrRge : FreqRange {1 byte – frequency scale range  
(10-20K,100-20K,1K-20K,10-2K,10-200 Hz)}

FrsFreqRes: FreqRes  
{48 octave)}

StartF : Single {4 bytes – first measurement frequency}  
StopF : Single {4 bytes – last measurement frequency}  
FrsSpeed : Speed {1 byte – sweep speed (fast, mid, slow)}  
Gtd : boolean {1 byte – switch for gated acquisition}  
GtdAutoPh : boolean {1 byte – switch for auto phase}  
GtdAutoPhFreq: Single {4 bytes – reference frequency for gated acquisition}  
GtdAutoMtDel: boolean {1 byte – switch for auto delay}  
GtdMtDel : Single {4 bytes – delay for gated acquisition}  
GtdMtOn : Single {4 bytes – sampling time for gated acquisition}  
THD : boolean {1 byte – switch for harmonic analysis}  
THD2Dysp : boolean {1 byte – switch for second harmonic analysis}  
THD3Dysp : boolean {1 byte – switch for third harmonic analysis}  
THDRiseVal: boolean {4 bytes – dB rise for harmonic analysis}

end;

FrsArray = array [0..535] of SinStruct; {6432 bytes – measurement data}

SinStruct = Record

Val : Complex = Record {value}

```

        Re : Single;           {4 bytes – real part}
        Im : Single;           {4 bytes – imag part}
    end;
    Freq : Single               {4 bytes – frequency}
End;

```

\*\* The following part is present only when harmonic analysis is enabled.

```

THD2Array = array [0..535] of SinStruct;   {6432 bytes – second harmonic data}
SinStruct = Record
    Val : Complex = Record   {value}
        Re : Single;         {4 bytes – real part}
        Im : Single;         {4 bytes – imag part}
    end;
    Freq : Single            {4 bytes – frequency}
End;
THD3Array = array [0..535] of SinStruct;   {6432 bytes – third harmonic data}
SinStruct = Record
    Val : Complex = Record   {value}
        Re : Single;         {4 bytes – real part}
        Im : Single;         {4 bytes – imag part}
    end;
    Freq : Single            {4 bytes – frequency}
End;

```

Total bytes count = variable.

## Sinusoidal Impedance files (“.IMP” extension)

```

WrHead = Record
    Nome      : String[11];      {12 bytes — usually “AUDIOMATICA”}
    Programma: String[8];        {9 bytes - usually “CLIO”}
    Release   : String[4];       {5 bytes - software release}
    Comm1     : String[40];      {41 bytes - comment}
    Comm2     : String[40];      {41 bytes - comment}
    Comm3     : String[40];      {41 bytes - comment}
    Comm4     : String[106];     {107 bytes - comment}
end;
IMPText = Record
    Titolo    : String[8];       {9 bytes – file name}
    Commento  : String[50];     {51 bytes – user comment (input with About)}
end;
IMPSet = Record
    OhmMax    : Single           {4 bytes – maximum graph value}
    OhmMin    : Single           {4 bytes – minimum graph value}
    LinLogY   : byte             {1 byte – kind of Y axis (linear, logarithmic)}
    Auto      : boolean          {1 byte – switch for auto display parameters}
    IMPFrRge  : FreqRange       {1 byte – frequency scale range
                                (10-20K, 100-20K, 1K-20K, 10-2K, 10-200 Hz)}
    IMPFreqRes: FreqRes         {1 byte – frequency resolution (1/3, 1/6, 1/12, 1/24, 1/
                                48 octave)}

```

```

StartF      : Single           {4 bytes – first measurement frequency}
StopF       : Single           {4 bytes – last measurement frequency}
FrsSpeed    : Speed            {1 byte – sweep speed (fast, mid, slow)}
Mode        : ImpMode          {1 byte – measurement mode (internal, constant I, constant V)}
ResVal      : Single           {4 bytes – sensing resistor value}
end;
IMPArray    = array [0..535] of SinStruct;    {6432 bytes – impedance data}
  SinStruct = Record
    Val      : Complex = Record    {value}
      Re     : Single;             {4 bytes – real part}
      Im     : Single;             {4 bytes – imag part}
    end;
    Freq     : Single              {4 bytes – frequency}
  End;

```

Total bytes count = 6774 bytes.

## Sinusoidal Parameters files (“.SML” extension)

```

WrHead = Record
  Nome      : String[11];         {12 bytes — usually “AUDIOMATICA”}
  Programma : String[8];         {9 bytes - usually “CLIO”}
  Release   : String[4];         {5 bytes - software release}
  Comm1     : String[40];        {41 bytes - comment}
  Comm2     : String[40];        {41 bytes - comment}
  Comm3     : String[40];        {41 bytes - comment}
  Comm4     : String[106];       {107 bytes - comment}
end;
SMLText = Record
  Titolo    : String[8];         {9 bytes – file name}
  Commento  : String[50];       {51 bytes – user comment (input with About)}
end;
Parameters : Record
  Manufacturer: String[20]       {21 bytes – Manufacturer’s name}
  Model       : String[20]       {21 bytes – Model’s name}
  ***        : String[11]       {12 bytes – reserved}
  Fs          : Single           {4 bytes – resonance frequency of driver}
  FsAdMa     : Single           {4 bytes – resonance frequency with added mass}
  FsKnVI     : Single           {4 bytes – resonance frequency with known volume}
  AdMass     : Single           {4 bytes – added mass}
  KnVol      : Single           {4 bytes – known volume}
  D          : Single           {4 bytes – diameter}
  Zm         : Single           {4 bytes – maximum impedance of driver}
  ***        : Single           {4 bytes – reserved}
  ***        : Single           {4 bytes – reserved}
  ZF1F2     : Single           {4 bytes – impedance of driver at –3 dB frequencies}
  F1        : Single           {4 bytes – lower frequency at –3 dB}
  F2        : Single           {4 bytes – upper frequency at –3 dB}
  Re        : Single           {4 bytes – DC resistance of voice coil}
  Rms       : Single           {4 bytes – mechanical resistance of driver suspension}

```

```

Qms      : Single          {4 bytes}
Qes      : Single          {4 bytes}
Qts      : Single          {4 bytes}
Cms      : Single          {4 bytes – mechanical compliance of suspension}
Mms      : Single          {4 bytes – mechanical mass of diaphragm}
Bl       : Single          {4 bytes – magnetic flux density}
Vas      : Single          {4 bytes – volume of air with same compliance of sus-
pension}
dBspl    : Single          {4 bytes – calculated at 1m with 2.83V}
L1K      : Single          {4 bytes – inductance at 1 KHz}
L10K     : Single          {4 bytes – inductance at 10 KHz}
Cas      : Single          {4 bytes – acoustical compliance of suspension}
***      : Single          {4 bytes – reserved}
***      : Single          {4 bytes – reserved}
***      : Single          {4 bytes – reserved}
SD       : Single          {4 bytes – effective area of diaphragm}
***      : array[0..10] of Single {44 bytes – reserved}
End;
ParamIMPArray= array [0..535] of SinStruct; {6432 bytes – impedance data}
  SinStruct = Record
    Val : Complex = Record {value}
      Re : Single; {4 bytes – real part}
      Im : Single; {4 bytes – imag part}
    end;
    Freq : Single {4 bytes – frequency}
  End;

```

Total bytes count = 6962 bytes.

## Sinusoidal Distortion files (“.DST” extension)

```

WrHead = Record
  Nome      : String[11]; {12 bytes — usually “AUDIOMATICA”}
  Programma : String[8]; {9 bytes - usually “CLIO”}
  Release   : String[4]; {5 bytes - software release}
  Comm1     : String[40]; {41 bytes - comment}
  Comm2     : String[40]; {41 bytes - comment}
  Comm3     : String[40]; {41 bytes - comment}
  Comm4     : String[106]; {107 bytes - comment}
end;
DSTText = Record
  Titolo    : String[8]; {9 bytes – file name}
  Commento  : String[50]; {51 bytes – user comment (input with About)}
end;
DSTData = Record
  THDFreq   : Single {4 bytes – THD frequency}
  CCIFFreq  : Single {4 bytes – CCIF frequency}
  Start     : Single {4 bytes – Start voltage}
  Stop      : Single {4 bytes – Stop voltage}
  ***      : Single {4 bytes – reserved}
  ***      : Single {4 bytes – reserved}

```

```

Load      : Single           {4 bytes – Load resistance}
Steps     : Single           {4 bytes – Number of steps}
end;DSTUnit : DSTUnitType   {1 byte – measurement unit (volts, watts)}
DSTKind   : DSTKindType     {1 byte – measurement kind (THD, SMPTE, DIN,
CCIF)}
DSTArray  = array [0..400] of DSTVal; {3208 bytes – impedance data}
  DSTVal = Record
    Lev    : Single;         {4 bytes – level}
    Dist   : Single         {4 bytes – distortion}
  End;

```

Total bytes count = 3558 bytes.

## Polar files (“.POL” extension)

```

WrHead = Record
  Nome      : String[11];    {12 bytes — usually “AUDIOMATICA”}
  Programma : String[8];    {9 bytes - usually “CLIO”}
  Release   : String[4];    {5 bytes - software release}
  Comm1     : String[40];   {41 bytes - comment}
  Comm2     : String[40];   {41 bytes - comment}
  Comm3     : String[40];   {41 bytes - comment}
  Comm4     : String[106];  {107 bytes - comment}
end;
POLText = Record
  Titolo    : String[8];    {9 bytes – file name}
  Commento  : String[50];   {51 bytes – user comment (input with About)}
End;
RTALocals = Record
  Fcamp     : Word;        {2 bytes – sampling frequency}
  Mode      : MisUnit;     {1 byte – measuring mode (Volt, Pressure)}
  MicASens  : Single;     {4 bytes – A channel sensitivity}
  MicBSens  : Single;     {4 bytes – B channel sensitivity}
  SensUnits : UnitsType;  {1 byte – sensitivity units (mV/Pa, dBV/Pa, dBspl/V)}
  MicCal    : Boolean;    {1 byte – microphone calibration switch}
  FullScale : Single;     {4 bytes – top of screen value}
  Channel   : AcquiMode;  {1 byte – input channel (A,B,A-B)}
end;
PolStruct = Record
  Freq      : Single;     {4 bytes – measurement frequency (Hz)}
  Step      : Single;     {4 bytes – measurement angle step (degrees)}
  Data      : array [0..71] of Single {288 bytes – polar data (dB)}
End;

```

Total bytes count = 630 bytes.

## RTA files (“.PNK” extension in 3.21, “.RTA” extension in 4.00)

```
WrHead = Record
Nome      : String[11];           {12 bytes — usually “AUDIOMATICA”}
Programma : String[8];           {9 bytes - usually “CLIO”}
Release   : String[4];           {5 bytes - software release}
Comm1     : String[40];          {41 bytes - comment}
Comm2     : String[40];          {41 bytes - comment}
Comm3     : String[40];          {41 bytes - comment}
Comm4     : String[106];         {107 bytes - comment}
end;
RTAText = Record
Titolo    : String[8];           {9 bytes – file name}
Commento  : String[50];         {51 bytes – user comment (input with About)}
End;
RTALocals = Record
Fcamp     : Word;               {2 bytes – sampling frequency}
Mode      : MisUnit;            {1 byte – measuring mode (Volt, Pressure)}
MicASens  : Single;            {4 bytes – A channel sensitivity}
MicBSens  : Single;            {4 bytes – B channel sensitivity}
SensUnits : UnitsType;         {1 byte – sensitivity units (mV/Pa, dBV/Pa, dBspl/V)}
MicCal    : Boolean;           {1 byte – microphone calibration switch}
FullScale : Single;            {4 bytes – top of screen value}
Channel   : AcquiMode;         {1 byte – input channel (A,B,A-B)}
end;
RTANuAver : integer;            {2 bytes – number of averages}
RTAAvgMod = array [0..30] of single; {124 bytes – RTA data}
RTAAvgTotMod= single;          {4 bytes – total level dB (linear)}
RTAAvgTotMod= single;          {4 bytes – total level dBA (A-weighted)}
```

Total bytes count = 468 bytes.

## RT60 files (“.T60” extension)

```
WrHead = Record
Nome      : String[11];           {12 bytes — usually “AUDIOMATICA”}
Programma : String[8];           {9 bytes - usually “CLIO”}
Release   : String[4];           {5 bytes - software release}
Comm1     : String[40];          {41 bytes - comment}
Comm2     : String[40];          {41 bytes - comment}
Comm3     : String[40];          {41 bytes - comment}
Comm4     : String[106];         {107 bytes - comment}
end;
T60Text = Record
Titolo    : String[8];           {9 bytes – file name}
Commento  : String[50];         {51 bytes – user comment (input with About)}
End;
T60Locals = Record
Fcamp     : Word;               {2 bytes – sampling frequency}
Mode      : MisUnit;            {1 byte – measuring mode (Volt, Pressure)}
```

```

MicASens : Single;           {4 bytes – A channel sensitivity}
MicBSens : Single;           {4 bytes – B channel sensitivity}
SensUnits : UnitsType;      {1 byte – sensitivity units (mV/Pa, dBV/Pa, dBspl/V)}
MicCal    : Boolean;         {1 byte – microphone calibration switch}
FullScale : Single;          {4 bytes – top of screen value}
Channel   : AcquiMode;       {1 byte – input channel (A,B,A-B)}
end;
T60SingState= array [0..7] of boolean {8 bytes – switch active for each measured octave}

```

\*\* For each measured octave the following data is appended

```

T60SinglePulse= array [0..16382] of single;{65532 bytes – measured octave impulse data}
T60NoCare = array [0..2] of byte; {3 bytes – no care data}
T60FileFCamp : integer; {2 bytes – measured octave sampling frequency}

```

Total bytes count = variable.

## Leq files (“.LEQ” extension)

```

LEQData : array[0..Samples] of single {4*Samples bytes – time history data}
WrHead = Record
  Nome : String[11]; {12 bytes — usually “AUDIOMATICA”}
  Programma : String[8]; {9 bytes - usually “CLIO”}
  Release : String[4]; {5 bytes - software release}
  Comm1 : String[40]; {41 bytes - comment}
  Comm2 : String[40]; {41 bytes - comment}
  Comm3 : String[40]; {41 bytes - comment}
  Comm4 : String[106]; {107 bytes - comment}
end;
LEQText = Record
  Titolo : String[8]; {9 bytes – file name}
  Commento : String[50]; {51 bytes – user comment (input with About)}
End;
LEQLocals = Record
  Fcamp : Word; {2 bytes – sampling frequency}
  Mode : MisUnit; {1 byte – measuring mode (Volt, Pressure)}
  MicASens : Single; {4 bytes – A channel sensitivity}
  MicBSens : Single; {4 bytes – B channel sensitivity}
  SensUnits : UnitsType; {1 byte – sensitivity units (mV/Pa, dBV/Pa, dBspl/V)}
  MicCal : Boolean; {1 byte – microphone calibration switch}
  FullScale : Single; {4 bytes – top of screen value}
  Channel : AcquiMode; {1 byte – input channel (A,B,A-B)}
end;
LEQSet = Record
  Mode : IntegrationType; {1 byte – kind of integration (slow, fast, impulse)}
  TimeUnit : Char; {1 byte – ‘s’ per second or ‘m’ per minute}
  dB : dBType; {1 bytes – equal dB or dBA}
  UnitPerDiv : integer; {2 bytes – number of units per time division}
  StopTime : longint; {4 bytes – integration stop time in s}
  CountPerSec : integer; {2 bytes – equal 8 (fast or slow) or 32 (impulse)}
End;

```

LEQValue	: Single	<i>{4 bytes – final Leq value}</i>
LEQMax	: Single	<i>{4 bytes – maximum level}</i>
LEQOvl	: Boolean	<i>{1 bytes – switch active when overload occurred during measure}</i>

Total bytes count = variable.

## Oscilloscope files (“.SPE” extension)

WrHead = Record

Nome	: String[11];	<i>{12 bytes — usually “AUDIOMATICA”}</i>
Programma	: String[8];	<i>{9 bytes - usually “CLIO”}</i>
Release	: String[4];	<i>{5 bytes - software release}</i>
Comm1	: String[40];	<i>{41 bytes - comment}</i>
Comm2	: String[40];	<i>{41 bytes - comment}</i>
Comm3	: String[40];	<i>{41 bytes - comment}</i>
Comm4	: String[106];	<i>{107 bytes - comment}</i>

end;

ScopeText = Record

Titolo	: String[8];	<i>{9 bytes – file name}</i>
Commento	: String[50];	<i>{51 bytes – user input comment (with About)}</i>

end;

Soglia	: integer;	<i>{2 bytes – trigger level index}</i>
AmplIndex	: integer;	<i>{2 bytes – vertical amplification index}</i>
TBIndex	: integer;	<i>{2 bytes – time base index}</i>
ScopeCh	: ChannelOn;	<i>{1 byte – display mode (A,B,A-B,Dual)}</i>
IntTrig	: boolean;	<i>{1 byte – internal trigger switch}</i>
IntTrigDly	: integer;	<i>{2 bytes – internal trigger delay}</i>
ScoS	= array [0..510] of integer;	<i>{1022 bytes – channel a data}</i>
ScoSb	= array [0..510] of integer;	<i>{1022 bytes – channel b data}</i>

Total bytes count = 2370 bytes.

## ‘CONV3TO4.EXE’ Translation software from release 3.21 to 4.00

The program CONV3TO4.EXE can be used to translate CLIO data files in the old 3.21 format to a format compatible with release 4.00. To avoid wrong results the following precautions have to be taken.

**NOTE 1: The conversion program has to be saved in and run from the C:\CLIO40\ directory.**

**NOTE 2: Before running the conversion program perform the standard CLIO 4 system calibration.**

The program directs the user with simple prompts while doing its job.